

Detection and Classification of Brain Tumor Using Machine Learning

Roshnadevi J. Sapkal,¹ Dr. Sharda L. Kore,² Sonal M. Patil³ Savita A. Itkarkar⁴ Roma R. Jain⁵

Department of Electronics and Telecommunication Engineering
Bharati Vidyapeeth's College of Engineering for Women, Pune-43

ABSTRACT

In this project, we propose a brain tumor segmentation and classification method for multi-modality magnetic resonance image scans. The data from multi-modal brain tumor segmentation challenge are utilized which are coregistered and skull stripped, and the histogram matching is performed with a reference volume of high contrast. We are detecting tumor by using preprocessing, segmentation, feature extraction, optimization and lastly classification after that preprocessed image use to classify the tissue. We performed a leave one out cross validation and achieved 88 Dice overlap for the complete tumor region, 75 for the core tumor region and 95 for enhancing tumor region, which is higher than the Dice overlap reported

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I. INTRODUCTION

The detection and diagnosis of brain tumor from MRI is crucial to decrease the rate of casualties. Brain tumor is difficult to cure, because the brain has a very complex structure and the tissues are interconnected with each other in a complicated manner.

Despite many existing approaches, robust and efficient segmentation of brain tumor is still an important and challenging task. Tumor segmentation and classification is a challenging task, because tumors vary in shape, appearance and location.

It is hard to fully segment and classify brain tumor from mono-modality scans, because of its complicated structure. MRI provides the ability to capture multiple images known as multimodality images, which can provide the detailed structure of brain to efficiently classify the brain tumor. shows different MRI modalities of brain.

MOTIVATION: We get motivated of existing system.

We have to match user object with database image using Spatial gray level dependencies method. In that system first we have pre-processing on those images then select feature extraction and compare brain with database and get the result.

OBJECTIVE: The main objective of this system is to detect

the tumor and classify the tissue of tumor area. Using the preprocessing, segmentation, feature extraction, optimization and classification.

II. NEED OF PROJECT

The detection and diagnosis of brain tumor from MRI is crucial to decrease the rate of casualties. Brain tumor is difficult to cure, because the brain has a very complex structure and the tissues are interconnected with each other in a complicated manner.

Despite many existing approaches, robust and efficient segmentation of brain tumor is still an important and challenging task. Tumor segmentation and classification is a challenging task, because tumors vary in shape, appearance and location. It is hard to fully segment and classify brain tumor from mono-modality scans, because of its complicated structure.

III. PAST WORK

Many research papers from reputed national and international journals are surveyed and few are presented here:

[1] Brain tumor detection and recognition from MRI scan. (2020)

This work proposes a fast and robust practical strategy to extract a brain tumor using patient's MRI scan images of the brain. For this purpose, some tools are used which include the basic concepts of image processing such as noise removal

functions, segmentation and morphological operations. To detect and extract a tumor from MRI scan, a MATLAB software code is implemented

[2] Classification of Brain Tumors from MRI images using a Convolutional Neural Network. (2020) More than one convolution layers with deep neural network is utilized for finding feature in neoplasm image. The utilization of diminutive kernels (3*3 or 5*5 size) sanctions designing a deeper design, besides having a positive impact against over fitting. The goal is classification with segmentation of tumor part with the help of convolutional neural network and Watershed Algorithm. In this paper the input to the system is considered as brain scanned MRI image.

[3] Individual Prediction of Brain Tumor Histological Grading using Radiomics on Structural MR. (2018) The goal was to predict tumor grade and cell type of individual patients using a radiomics study with Random Forests. In a multiclass design, we obtain a global accuracy of 59.9% to predict tumor grade and 53.4% to predict cell type. Converting the problem to binary classification, we obtain an accuracy of 98.3% to distinguish between meningioma and glioma, and 84.5% to distinguish between low-grade glioma and glioblastoma.

[4] Brain tumor detection based on Naïve Bayes Classification (2019) In this paper, Naïve Bayes classification is utilized for recognition of a tumor region accurately that contains all spreading cancerous tissues. Brain MRI database, preprocessing, morphological operations, pixel subtraction, maximum entropy threshold, statistical features extraction, and Naïve Bayes classifier-based prediction algorithm are used in this research. The goal of this method is to detect the tumor area from different brain MRI images and to predict that detected area whether it is a tumor or not.

[5] Brain Tumor Detection Using Machine Learning (2020) This paper discusses such a machine learning algorithm that can write the user about the details of the tumor using brain MRI. These methods include noise removal and sharpening of the image along with basic morphological functions, erosion, and dilation, to obtain the background.

IV. PROPOSED METHODOLOGY

Present system consist of

A. Software:

Operating system: Windows 10

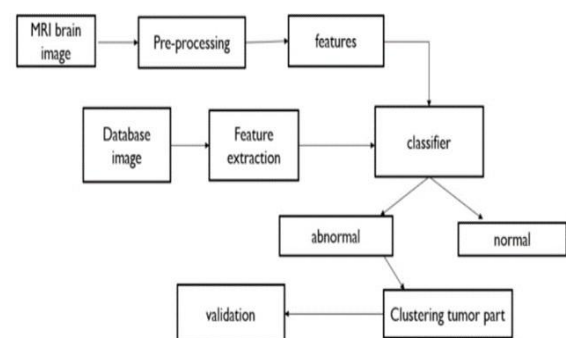
Coding Language: Python

IDE: Spyder

Packages: Numpy, OpenCV, Tensorflow, keras, Matplotlib

B. System Architecture

In this system first we are going to apply an input image of Soyabean leaves to the system then it will preprocess the image and according to disease it will decide pesticide for particular disease and this information is supplied to pesticides supplier.



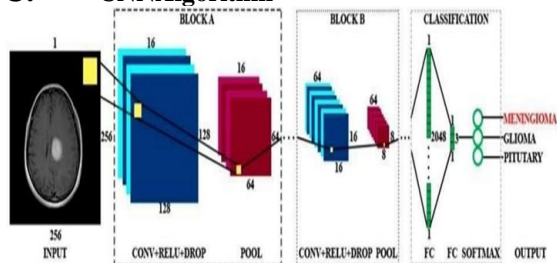
PREPROCESSING: - In our pre-processing the input image data is converted into meaningful floating-point tensors for feeding into Convolutional Neural Networks. Just for the knowledge tensors are used to store data, they can be assumed as multidimensional arrays. A tensor representing a 64 X 64 image having 3 channels will have its dimensions (64, 64, 3). Currently, the data is stored on a drive as JPEG files, so let's see the steps taken to achieve it. 1. Read the picture files (stored in data folder). Decode the JPEG content to RGB grids of pixels with channels. 2. Convert these into floating-point tensors for input to neural nets. 3. Rescale the pixel values (between 0 and 255) to the [0, 1] interval (a training neural network with this range is efficient).

FEATURE EXTRACTION: - When performing deep learning feature extraction, we treat the pre-trained network as an arbitrary feature extractor, allowing the input image to propagate forward, stopping at pre-specified layer, and taking the outputs of that layer as our features. Doing so, we can still utilize the robust, discriminative features learned by the CNN. We can also use them to recognize classes the CNN was never trained on! Feature extraction is a part of the dimensionality reduction process, in which, an initial set of the raw data is divided and reduced to more manageable groups. These features are easy to

process, but still able to describe the actual data set with the accuracy and originality.

CLASSIFICATION CNN:- As in any other neural network, the input of a CNN, in this case an image, is passed through a series of filters in order to obtain a labeled output that can then be classified. The specificity of a CNN lies in its filtering layers, which include at least one convolution layer. These allow to process more complex pictures than a regular neural network. Whereas the latter is well adapted for simple, well-centered images such as hand-written digits, the use of CNNs in image analysis ranges from Face-book's automatic tagging algorithms, to object classification and detection, in particular in the field of radiology. Convolutional Neural Networks specialized for applications in image video recognition. CNN is mainly used in image analysis tasks like Image recognition, Object detection, Segmentation.

C. CNN Algorithm



A Convolutional Neural Network (ConvNet/CNN) is a Deep Learning algorithm which can take in an input image, assign importance (learnable weights and biases) to various aspects/objects in the image and be able to differentiate one from the other. The architecture of a ConvNet is analogous to that of the connectivity pattern of neurons in the Human Brain and was inspired by the organization of the Visual Cortex. Individual neurons respond to stimuli only in a restricted region of the visual field known as the Receptive Field. A collection of such fields overlap to cover the entire visual area.

Algorithm step: - Step 1(a):

Convolution Operation:- The first building block in our plan of attack is convolution operation. In this step, we will touch on feature detectors, which basically serve as neural network's filters. We will also discuss feature maps, learning the parameters of such maps, how patterns are detected, the layers of detection, and how the findings are mapped out.

Step 1(b): ReLU Layer:- The second part of this step will involve the Rectified Linear Unit or ReLU. We will cover ReLU layers and explore how linearity functions in the context of 29

Convolutional Neural Networks. Not necessary for understanding CNN's, but there's no harm in a quick lesson to improve your skills.

Step 2: Pooling:-

In this part, we'll cover pooling and will get to understand exactly how it generally works. Pooling Layers section would reduce the number of parameters when the images are too large. Our next step, however, will be a specific type of pooling; max pooling.

Max pooling-

It takes the largest element in the feature map.

Mean pooling-

It takes the average of elements in the feature map.

Sum pooling-

It takes the sum of all elements in the feature map.

Step 3: Flattening:- This will be a brief breakdown

of the flattening process and how we move from pooled to flattened layers when working with Convolutional Neural Network.

Step 4: Full Connection:-

In this part, everything that we covered throughout the section will be merged together. With the fully connected layers, combined these features together to create a model for classifying input image into various classes based on training set.

D. Software Information

Python: Python is an interpreted, high-level and general-purpose programming language. Created

by Guido van Rossum and first released in 1991, Python's design philosophy emphasizes code readability with its notable use of significant whitespace. Its language constructs and object-oriented approach aim to help programmers write clear, logical code for small and large-scale projects.

Python is dynamically typed and garbage-collected. It supports multiple programming paradigms, including structured (particularly, procedural), object-oriented, and functional programming. Python is often described as a "batteries included" language due to its comprehensive standard library.

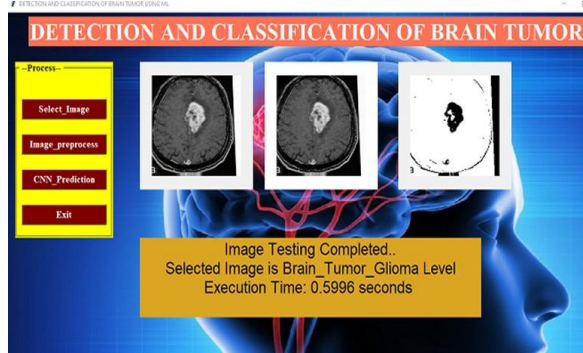
Python interpreters are available for many operating systems. A global community of programmers develops and maintains CPython, a free and open-source reference implementation. A non-profit organization, the Python Software Foundation, manages and directs resources for Python and CPython development. Python was conceived in the late 1980s by Guido van Rossum at Centrum Wiskunde Informatica (CWI) in the Netherlands as a successor to the ABC language (itself inspired by SETL), capable of exception

handling and interfacing with the Amoeba operating system. Its implementation began in December 1989.

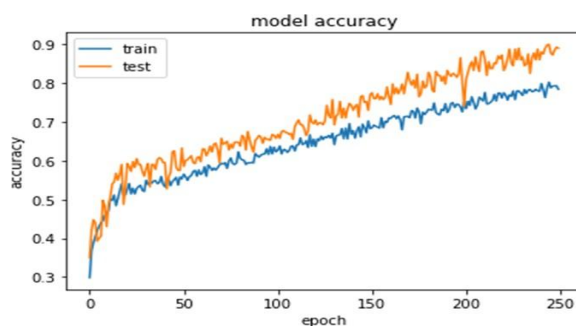
Anaconda: Anaconda is a free and open-source distribution of the Python and R programming language for scientific computing (data science, machine learning applications, large-scale data processing, predictive analytics, etc.), that aims to simplify package management and deployment. The distribution includes data science packages suitable for Windows, Linux, and macOS. It is developed and maintained by Anaconda, Inc., which was founded by Peter Wang and Travis Oliphant in 2012. As an Anaconda, Inc. product, it is also known as Anaconda Distribution or Anaconda Individual Edition.

Spyder: Spyder is an open-source integrated development environment (IDE) used in computer programming, specifically for the Python language. It is developed by the Spyder project contributors. Spyder integrates with a number of prominent packages in the scientific Python stack, including NumPy, SciPy, Matplotlib, pandas, IPython, as well as other open source software. Spyder is cross-platform, with Windows, macOS and Linux versions.

V. RESULT & OUTPUTS



Test and Accuracy:



VI. FUTURE SCOPE

- In near future, a database can be created for different patients having different types of

brain tumors and locate them.

- This application can be extended to accessibility and usability through mobile phones.
- If this application is developed to analyze all types of MRI scans of same patient and result of all scans are integrated, it can suggest appropriate treatment and medication as well.

VII. CONCLUSION

In this proposed work different medical images like MRI brain images are taken for detecting tumor. The proposed approach for brain tumor detection supported convolution neural network categorizes into multilayer perceptron neural network. The proposed approach utilizes a mixture of this neural network technique and consists of several steps including training the system, pre-processing, segmentation and classification. In the future, we'll take an outsized database and check out to offer more accuracy which can work on any sort of MRI brain tumor.

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